

# Vector H320 GNSS Compass Module

## Advanced Heading & RTK Positioning



### Vector H320

### **Eclipse™**

Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vector H320™ is our most advanced GNSS heading and positioning module available from Hemisphere GPS.

The Vector H320 utilizes dual antenna ports to create a series of additional capabilities to Eclipse™ Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard L-band reception, RTK-enabled heave, low power consumption and precise timing.

Integrate the Vector H320 into your applications to experience exceptional performance, flexibility and cost savings. This incredible GNSS module uses advanced multipath mitigation techniques and offers full scalability and expandability from L1/L2 GPS/GLONASS to L1/L2 GPS/GLONASS RTK performance.

## Key Vector H320 GNSS Compass Module Advantages

- Extremely accurate heading with short baselines
- L1/L2 GPS/GLONASS RTK capable
- L-band (OmniSTAR®) capable
- Fast RTK acquisition and reacquisition times
- Excellent coasting performance
- 5 cm rms RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection

# Vector H320 GNSS Compass Module

## GPS Sensor Specifications

Receiver Type:	Dual GNSS RTK	
Signals Received:	GPS, GLONASS, and GALILEO <sup>7</sup>	
GPS Sensitivity:	-142 dBm	
SBAS Tracking:	3-channel, parallel tracking	
Update Rate:	10 Hz standard, 20 Hz optional	
Horizontal Accuracy:	RMS (67%)	2DRMS (95%)
RTK: <sup>1</sup>	10 mm + 1 ppm	20 mm + 2 ppm
L-band (OmniSTAR): <sup>2,8</sup>	0.08 m	0.16 m
SBAS (WAAS): <sup>2</sup>	0.25 m	0.50 m
Autonomous, no SA: <sup>2</sup>	1.20 m	2.50 m
Heading Accuracy:	$< 0.17^\circ$ rms @ 0.5 m antenna separation $< 0.09^\circ$ rms @ 1.0 m antenna separation $< 0.04^\circ$ rms @ 2.0 m antenna separation $< 0.02^\circ$ rms @ 5.0 m antenna separation	
Pitch / Roll Accuracy:	$< 1^\circ$ rms	
Heave Accuracy:	30 cm rms (DGPS) <sup>6</sup> , 5 cm rms (RTK) <sup>6</sup>	
Timing (1PPS) Accuracy:	20 ns	
Rate of Turn:	100°/s maximum	
Cold Start:	$< 40$ s typical (no almanac or RTC)	
Warm Start:	$< 20$ s typical (almanac and RTC)	
Hot Start:	$< 5$ s typical (almanac, RTC and position)	
Heading Fix:	$< 10$ s typical (Hot Start)	
Antenna Input Impedance:	50 $\Omega$	
Maximum Speed:	1,850 kph (999 kts)	
Maximum Altitude:	18,288 m (60,000 ft)	

## L-band Sensor Specifications

Sensitivity:	-130 dBm
Channel Spacing:	7.5 kHz
Satellite Selection:	Manual and Automatic
Reacquisition Time:	15 seconds (typical)
Rejection:	15 kHz spacing $> 30$ dB, 300 kHz spacing $> 60$ dB
Processor:	DSP for demodulation and protocol decoding module provides processing for the differential algorithms
Command Support:	Reports L-band (OmniSTAR) region, satellite info, allows input and status of L-band (OmniSTAR) subscription, Bit Error Rate output for reception quality indication and manual frequency tuning

## Communications

Serial Ports:	4 full-duplex 3.3 V CMOS (3 main serial ports, 1 differential-only port), 1 USB Host, 1 USB Device
Baud Rates:	4800 - 115200
Correction I/O Protocol:	RTCM SC-104, L-Dif <sup>TM</sup> , RTCM v2.3 (DGPS), RTCM v3 (RTK), CMR, CMR+
Data I/O Protocol:	NMEA 0183, Crescent binary <sup>3</sup> , L-Dif
Timing Output:	1PPS, CMOS, active low, falling edge sync, 10 k $\Omega$ , 10 pF load
Event Marker Input:	CMOS, active low, falling edge sync, 10 k $\Omega$ , 10 pF load
Heading Warning I/O:	Pin 62

## Power

Input Voltage:	3.3 VDC +/- 5%
Power Consumption:	$< 3.2$ W at 3.3 V (L1/L2 GPS/GLONASS)
Current Consumption:	$< 970$ mA at 3.3 V (L1/L2 GPS/GLONASS)
Power Consumption:	$< 3.9$ W at 3.3 V (L1/L2 GPS/GLONASS; L-band)
Current Consumption:	$< 1180$ mA at 3.3 V (L1/L2 GPS/GLONASS; L-band)
Antenna Voltage:	15 VDC maximum
Antenna Short Circuit Protection:	Yes
Antenna Gain Input Range:	10 to 40 dB
Antenna Input Impedance:	50 $\Omega$

## Environmental

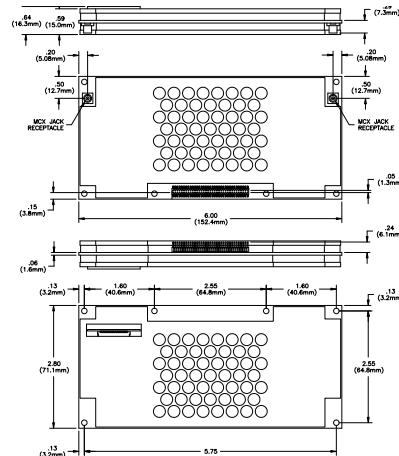
Operating Temperature:	-40°C to +85°C (-40°F to +185°F)
Storage Temperature:	-40°C to +85°C (-40°F to +185°F)
Humidity:	95% non-condensing (when installed in an enclosure)

## Mechanical

Dimensions:	15.2 L x 7.1 W x 1.6 H (cm) 6.0 L x 2.8 W x 0.63 H (in)
Weight:	.105 kg (3.70 oz.)
Status Indication (LED):	Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-band lock
Power/Data Connector:	70-pin male header, 0.05" pitch (1.27 mm)
Antenna Connectors:	MCX, female, straight

## Aiding Devices

Gyro:	Provides smooth heading, fast heading reacquisition and reliable $< 0.5^\circ$ per min heading for periods up to 3 min. when loss of GPS has occurred <sup>4</sup>
Tilt Sensors:	Provide pitch, roll data and assist in fast start-up and reacquisition of heading solution



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<sup>1</sup> Depends on multipath environment, antenna selection, number of satellites in view, satellite geometry, baseline length (for local services), and ionospheric activity  
<sup>2</sup> Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity  
<sup>3</sup> Hemisphere GPS proprietary  
<sup>4</sup> Under static conditions  
<sup>5</sup> This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation  
<sup>6</sup> Based on a 40 second time constant  
<sup>7</sup> Upgrade required  
<sup>8</sup> Requires a subscription from OmniSTAR